CINFRANOR[®]

XtrapulsPacHP™ AC servo drive



Really outstanding servo performances!

Power range

230VAC : 5 ... 17Arms max. 480VAC : 8 ... 200Arms max.

Interfaces

Fieldbuses: CANopen[®], EtherCAT[®], PROFINET[®] RS-232 USB port Digital and analog Inputs/Outputs

Sensors

Resolver Encoders: incremental, absolute, Hall effect sensor Digital encoders: Hiperface DSL®, EnDat 2.2®, BiSS C

Safety

Integrated Safe Torque Off function STO SIL 3 (standard) Motion safety functions (optional)

Functions

DS402 standard modes Electronic gearing, camming, stepper emulation Analog speed drive, stand-alone positioner

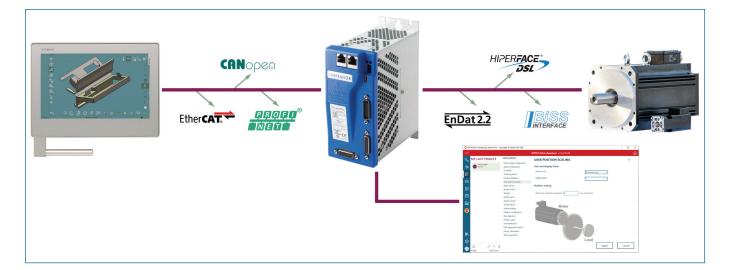
XtrapulsPacHP[™], servo drive for brushless AC motors

The XtrapulsPacHP[™] servo drive is a particularly compact and flexible device with outstanding capabilities. It provides many functions and interfaces to cover a wide range of single- and multi-axis applications. This drive is available for push-through, coldplate and wall mounting. It is fully compatible with the former XtrapulsPac[™] version.

Electrical specifications Drive type PacHP-230 PacHP-400 PacHP-400 Power supply type GDPS-400⁴ / 05 / 11 / 17 / 08 / 20 / 45³ / 100³ / 200³ / 16 / 32 / 64 20 Peak current [Arms] 5 11 17 8 45 100 200 Rated power 16kW 32kW 64kW 4 10 Cont. current [Arms] 2.5 5.5 8.5 22.5 35 75 Voltage 3x230VAC/3x480VAC 1x230VAC1/320VDC2 3x480VAC1/680VDC2 Voltage 680VDC² ⁴Integrated mains filter, DC bus output for parallel

³ Pending versions

¹Integrated power supply ²External power supply



Control loops

- -Digital drive for synchronous AC motors
- Current loop sampling: 31,25µs (PWM 16kHz), 62,5µs (PWM 8kHz)
- Speed and position loop sampling: $125\mu s$, $250\mu s$, $500\mu s$ (selectable)
- -Max. speed up to 25'000rpm
- Cogging torque compensation

Feedbacks

- -Resolver
- -Incremental encoder
- -Hall effect sensor
- SinCos encoder
- Single and multi-turn Hiperface® encoder
- Digital encoders: Hiperface DSL[®] (one single motor cable), EnDat 2.2[®], BiSS C

Communication interfaces

- –USB service port or RS-232
- CANopen[®], EtherCAT[®] or PROFINET[®] fieldbuses
- -DIP switches for node addressing

I/O interfaces

- User configurable digital I/Os
- Analog inputs \pm 10V / 16 bit
- Analog output 0 5V / 12 bit
- "AOK" relay output
- Motor brake control

Operation modes

DS402 standard modes

- Cyclic synchronous position
- Cyclic synchronous velocity
- Cyclic synchronous torque
- Interpolated position
- -Profile position
- Profile velocity
- Profile torque
- –Homing

Extended modes

- Analog speed
- -Stepper emulation
- Sequences
- Master-slave gearing
- Master-slave camming
- Electronic gearing

Safety features

- -STO SIL 3
- -SS1 / SS2 / SOS / SLS / SDI / SBC

connection of several drives, external braking resistor

Multi-axis toolbox

Configuration tools

- Motor and drive configuration
- Application configuration
- -Interface configuration
- -Auto-tuning, auto-phasing
- -Sequencer programming
- Motor libraries
- Multilingual software

Diagnostic tools

- Multi-axis oscilloscope
- Device control
- Device monitoring
- Object dialog window

Certifications



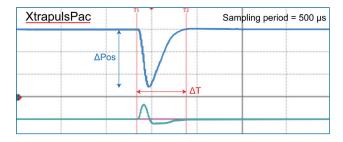
*UL listing pending

XtrapulsPacHP[™] can easily be configured as a stand-alone drive in various operation modes. It can also be integrated into an automation system with PLC, CNC or motion controller via the fieldbus and uses well-known standard functions available in libraries. This flexibility makes it suitable for use in a wide field of machines and applications with demanding specifications.

Dynamic servo performances

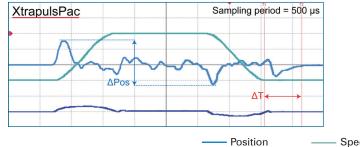
With regard to the former version XtrapulsPac[™], dynamic servo performances are increased by a factor of 3. The position error as well as the response time are divided by 3.

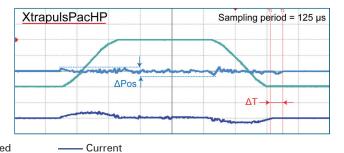
The position deviation for a step-like torque disturbance applied to the motor shaft is evaluated (stiffness test).



XtrapulsPacHP	Sampling period = 125 μs
ΔPos	V
→	

The position following error in profile position mode with an S-curve trajectory shape is evaluated (accuracy test).

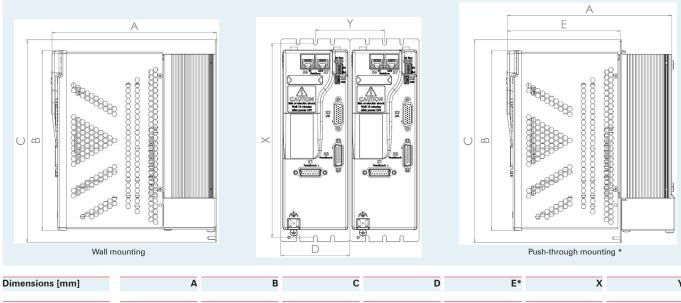




Speed

Tests were made with BLS 72A servo motor and 230V / 17A servo drives.

Mechanical dimensions [mm]



PacHP-230 V / 5 - 17 A	148	153	178	70		169	80
PacHP-400 V / 8 - 45 A	191	208	235	70 (80*)	131	225	80
PacHP-400 V / 100 A	214	208	235	80 (80*)	128	225	80
PacHP-400 V / 200 A	215	265	295	166.6	-	285	100
GDPS-400 V / 16/32 kW	158	203	235	70		225	80
GDPS-400 V / 64 kW	207	262.5	295	71.5	-	285	80

Infranor® product range



Infranor Group

Infranor creates added value for its customers by providing tailor-made motion solutions.

Based on strong working relationships, Infranor offers extensive market know-how, comprehensive engineering skills and a wide range of high-quality products leading to productivity gains and therefore to comparative advantages for its customers in their respective markets.

Infranor worldwide

Benelux China France Germany Italy Spain Switzerland UK USA

Other representations: Austria, Denmark, India, Israel, Poland, Slovenia, Turkey.

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