## **CINFRANOR**<sup>®</sup>

## XtrapulsPacHP™ AC servo drive



# Really outstanding servo performances!

#### **Power range**

230VAC : 5 ... 17Arms max. 480VAC : 8 ... 200Arms max.

#### Interfaces

Fieldbuses: CANopen<sup>®</sup>, EtherCAT<sup>®</sup>, PROFINET<sup>®</sup> RS-232 USB port Digital and analog Inputs/Outputs

#### Sensors

Resolver Encoders: incremental, absolute, Hall effect sensor Digital encoders: Hiperface DSL®, EnDat 2.2®, BiSS C

#### Safety

Integrated Safe Torque Off function STO SIL 3 (standard) Motion safety functions (optional)

### **Functions**

DS402 standard modes Electronic gearing, camming, stepper emulation Analog speed drive, stand-alone positioner

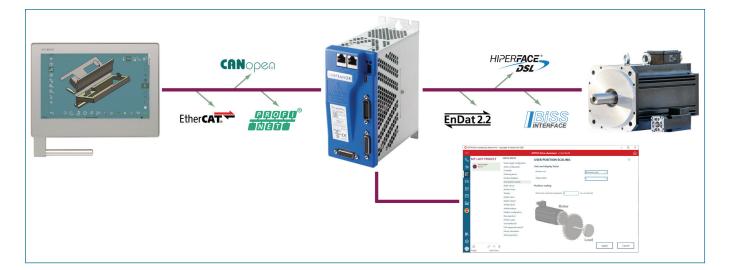
### XtrapulsPacHP<sup>™</sup>, servo drive for brushless AC motors

The XtrapulsPacHP<sup>™</sup> servo drive is a particularly compact and flexible device with outstanding capabilities. It provides many functions and interfaces to cover a wide range of single- and multi-axis applications. This drive is available for push-through, coldplate and wall mounting. It is fully compatible with the former XtrapulsPac<sup>™</sup> version.

#### **Electrical specifications** Drive type PacHP-230 PacHP-400 PacHP-400 Power supply type GDPS-400<sup>4</sup> / 05 / 11 / 17 / 08 / 20 / 45<sup>3</sup> / 100<sup>3</sup> / 200<sup>3</sup> / 16 / 32 / 64 20 Peak current [Arms] 5 11 17 8 45 100 200 Rated power 16kW 32kW 64kW 4 10 Cont. current [Arms] 2.5 5.5 8.5 22.5 35 75 Voltage 3x230VAC/3x480VAC 1x230VAC1/320VDC2 3x480VAC1/680VDC2 Voltage 680VDC<sup>2</sup> <sup>4</sup>Integrated mains filter, DC bus output for parallel

<sup>3</sup> Pending versions

<sup>1</sup>Integrated power supply <sup>2</sup>External power supply



#### **Control loops**

- -Digital drive for synchronous AC motors
- Current loop sampling: 31,25µs (PWM 16kHz), 62,5µs (PWM 8kHz)
- Speed and position loop sampling:  $125\mu s$ ,  $250\mu s$ ,  $500\mu s$  (selectable)
- -Max. speed up to 25'000rpm
- Cogging torque compensation

#### Feedbacks

- -Resolver
- -Incremental encoder
- -Hall effect sensor
- SinCos encoder
- Single and multi-turn Hiperface® encoder
- Digital encoders: Hiperface DSL<sup>®</sup> (one single motor cable), EnDat 2.2<sup>®</sup>, BiSS C

#### Communication interfaces

- –USB service port or RS-232
- CANopen<sup>®</sup>, EtherCAT<sup>®</sup> or PROFINET<sup>®</sup> fieldbuses
- -DIP switches for node addressing

#### I/O interfaces

- User configurable digital I/Os
- Analog inputs  $\pm$  10V / 16 bit
- Analog output 0 5V / 12 bit
- "AOK" relay output
- Motor brake control

#### Operation modes

#### DS402 standard modes

- Cyclic synchronous position
- Cyclic synchronous velocity
- Cyclic synchronous torque
- Interpolated position
- -Profile position
- Profile velocity
- Profile torque
- –Homing

#### Extended modes

- Analog speed
- -Stepper emulation
- Sequences
- Master-slave gearing
- Master-slave camming
- Electronic gearing

#### Safety features

- -STO SIL 3
- -SS1 / SS2 / SOS / SLS / SDI / SBC

connection of several drives, external braking resistor

#### **Multi-axis toolbox**

#### **Configuration tools**

- Motor and drive configuration
- Application configuration
- -Interface configuration
- -Auto-tuning, auto-phasing
- -Sequencer programming
- Motor libraries
- Multilingual software

#### **Diagnostic tools**

- Multi-axis oscilloscope
- Device control
- Device monitoring
- Object dialog window

#### Certifications



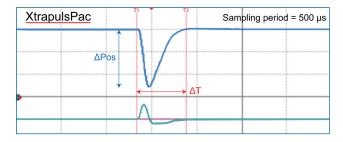
\*UL listing pending

XtrapulsPacHP<sup>™</sup> can easily be configured as a stand-alone drive in various operation modes. It can also be integrated into an automation system with PLC, CNC or motion controller via the fieldbus and uses well-known standard functions available in libraries. This flexibility makes it suitable for use in a wide field of machines and applications with demanding specifications.

#### **Dynamic servo performances**

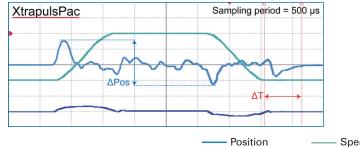
With regard to the former version XtrapulsPac<sup>™</sup>, dynamic servo performances are increased by a factor of 3. The position error as well as the response time are divided by 3.

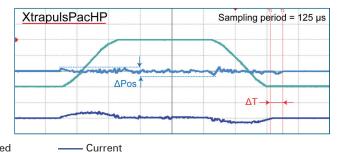
The position deviation for a step-like torque disturbance applied to the motor shaft is evaluated (stiffness test).



XtrapulsPacHP	Sampling period = 125 μs
ΔPos	V
→	

The position following error in profile position mode with an S-curve trajectory shape is evaluated (accuracy test).

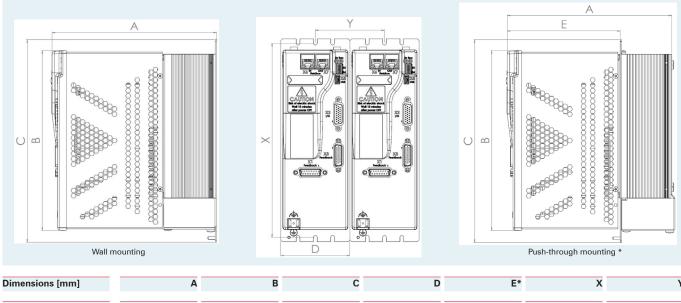




Speed

Tests were made with BLS 72A servo motor and 230V / 17A servo drives.

#### **Mechanical dimensions [mm]**



PacHP-230 V / 5 - 17 A	148	153	178	70		169	80
PacHP-400 V / 8 - 45 A	191	208	235	70 (80*)	131	225	80
PacHP-400 V / 100 A	214	208	235	80 (80*)	128	225	80
PacHP-400 V / 200 A	215	265	295	166.6	-	285	100
GDPS-400 V / 16/32 kW	158	203	235	70		225	80
GDPS-400 V / 64 kW	207	262.5	295	71.5	-	285	80

## Infranor® product range



#### **Infranor Group**

Infranor creates added value for its customers by providing tailor-made motion solutions.

Based on strong working relationships, Infranor offers extensive market know-how, comprehensive engineering skills and a wide range of high-quality products leading to productivity gains and therefore to comparative advantages for its customers in their respective markets.

#### Infranor worldwide

Benelux China France Germany Italy Spain Switzerland UK USA

Other representations: Austria, Denmark, India, Israel, Poland, Slovenia, Turkey.

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